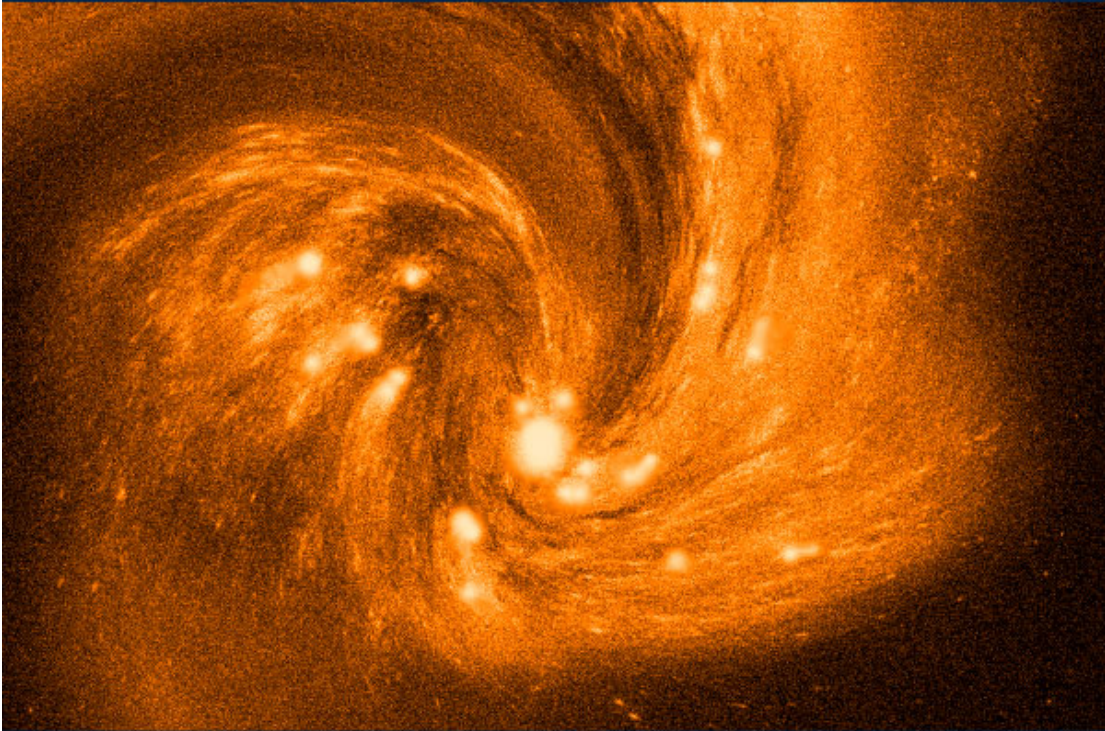


A-LEVEL MATHS TUTOR

Pure Maths



PART SEVEN

VECTORS

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General Properties of Vectors

Notation

A non-zero vector has the magnitude of a positive real number and a direction in space.

A vector may be represented by two letters describing a line. The order of the letters indicates the direction and the length of the line its magnitude.

$$\text{vector } \overrightarrow{AB} \qquad \text{magnitude } |\overrightarrow{AB}|$$

An alternative to this notation is to use a single bold letter, for example **C**. Then the magnitude is $|\mathbf{C}|$ or C .

The Unit Vector

A unit vector eg \mathbf{a} , has a magnitude of one $|\mathbf{a}|=1$ and can point in any direction.

Sometimes a unit vector is written with an accent over it $\hat{\mathbf{a}}$.

Different unit vectors point in different directions.

Hence, if \mathbf{F} is an ordinary vector,

$$\frac{\mathbf{F}}{|\mathbf{F}|} = \hat{\mathbf{F}}$$

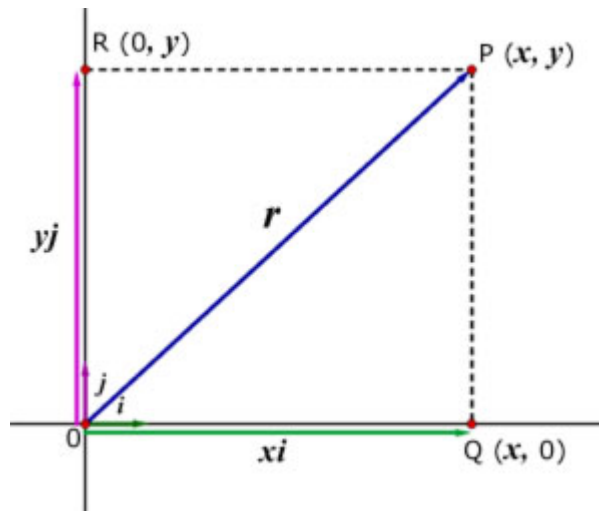
a unit vector in the direction of \mathbf{F} (^ circumflex accent)

2D representation

P is a point in the x - y plane with coordinates (x,y) . \mathbf{i} is the unit vector along the x -axis and \mathbf{j} is the unit vector along the y -axis.

With Q at $(x,0)$ and R at $(0, y)$:

$$\begin{aligned}\therefore \overrightarrow{OP} &= \overrightarrow{OQ} + \overrightarrow{QP} \\ &= \overrightarrow{OQ} + \overrightarrow{OR} \\ \Rightarrow \mathbf{r} &= x\mathbf{i} + y\mathbf{j}\end{aligned}$$

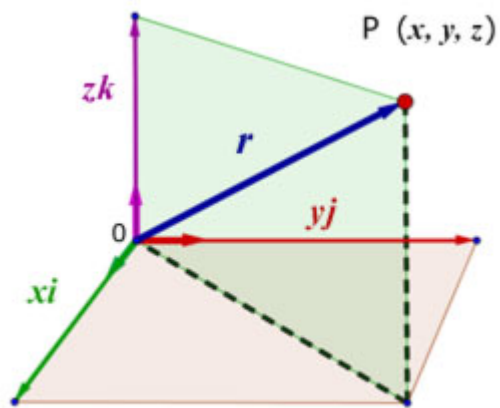


3D representation

P is a point in x - y - z space with coordinates (x, y, z) . \mathbf{i} is the unit vector along the x -axis, \mathbf{j} is the unit vector along the y -axis and \mathbf{k} is the unit vector along the z -axis.

$$\overrightarrow{OP} = \mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

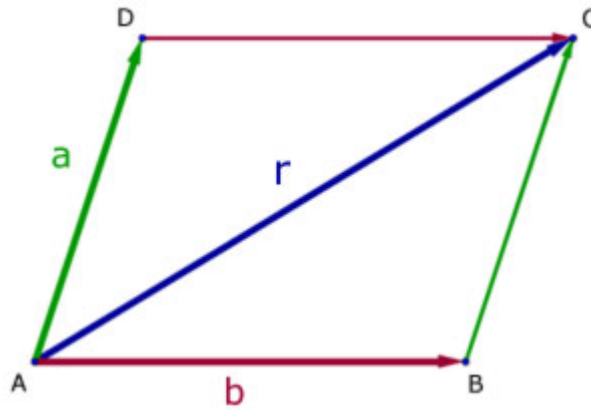
$$\begin{aligned} \text{length } OP &= |\overrightarrow{OP}| \\ &= \sqrt{(x^2 + y^2 + z^2)} \end{aligned}$$



Addition(Sum) of vectors

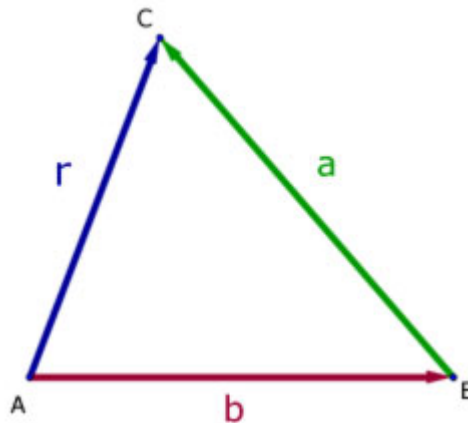
This is also called the Parallelogram or Triangle Law.

If two vectors(**a** & **b**) are represented in magnitude and direction by the adjacent sides of a **parallelogram** from a point, then their resultant(**r**) is represented in magnitude and direction by the diagonal of the parallelogram passing through the point.



$$\begin{aligned}\vec{AB} + \vec{AD} &= \vec{AC} \\ a &= \vec{AB} \quad b = \vec{AD} \\ a + b &= r\end{aligned}$$

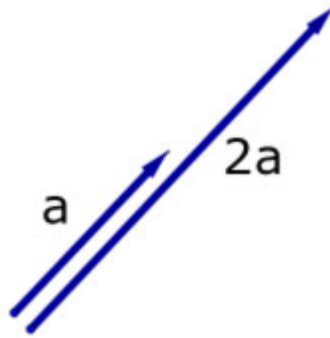
If two vectors are represented in magnitude and direction by the adjacent sides of a **triangle**, taken in order, then their resultant is represented in magnitude but opposite in direction by the third side.



$$\begin{aligned}\vec{AB} + \vec{BC} &= \vec{AC} \\ b &= \vec{AB} \quad a = \vec{BC} \\ b + a &= r\end{aligned}$$

Scalar Multiplication

Multiplying a vector by a scalar quantity changes its magnitude but not its direction.



Vector Equations

Component rules

Consider two vectors:

$$\mathbf{a} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k} \quad \text{and} \quad \mathbf{b} = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k}$$

in three dimensional space.

$$\mathbf{a} = \mathbf{b} \text{ implies that } x_1 = x_2 \quad y_1 = y_2 \quad z_1 = z_2$$

$$\mathbf{a} + \mathbf{b} = (x_1 + x_2)\mathbf{i} + (y_1 + y_2)\mathbf{j} + (z_1 + z_2)\mathbf{k}$$

$$\mathbf{a} - \mathbf{b} = (x_1 - x_2)\mathbf{i} + (y_1 - y_2)\mathbf{j} + (z_1 - z_2)\mathbf{k}$$

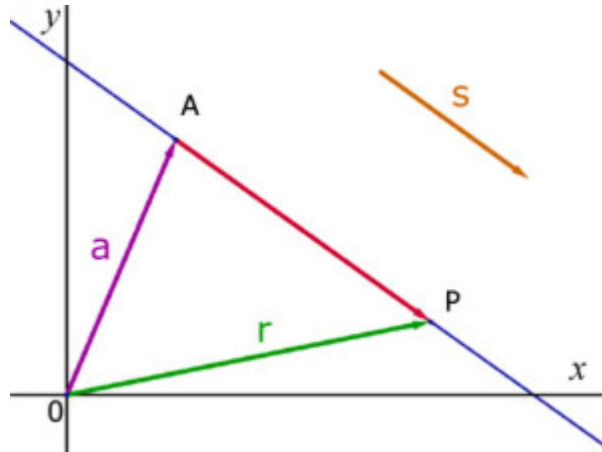
$$m\mathbf{a} = mx_1\mathbf{i} + my_1\mathbf{j} + mz_1\mathbf{k} \quad \text{where } m \text{ is a scalar quantity}$$

$$|\mathbf{a}| = \sqrt{(x_1^2 + y_1^2 + z_1^2)} \quad |\mathbf{b}| = \sqrt{(x_2^2 + y_2^2 + z_2^2)}$$

in 3D space, if point A has position vector \mathbf{a} and point B has position vector \mathbf{b} then the distance AB is given by:

$$\begin{aligned} AB &= |\overrightarrow{AB}| = |\mathbf{b} - \mathbf{a}| \\ &= \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2} \end{aligned}$$

Equation of a straight line - single point & parallel vector given



$A(x_1, y_1, z_1)$ is a fixed point on the line

\mathbf{a} is the position vector for point A $\mathbf{a} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k}$

\mathbf{s} is a vector parallel to the line $\mathbf{s} = l\mathbf{i} + m\mathbf{j} + n\mathbf{k}$
 (l, m, n are called the direction ratios of the line)

\mathbf{r} is the position vector for an arbitrary point $P(x, y, z)$ on the line.

\overrightarrow{AP} is parallel to s

$$\Rightarrow \overrightarrow{AP} = \sigma s \quad (\sigma \text{ is a scalar variable})$$

$$\Rightarrow \underline{r = a + \sigma s} \quad (\text{vector equation of the line})$$

substituting for a and s

$$r = x_1i + y_1j + z_1k + \sigma(li + mj + nk)$$

expanding and rearranging

$$r = (x_1 + \sigma l)i + (y_1 + \sigma m)j + (z_1 + \sigma n)k$$

$$r = xi + yj + zk$$

comparing the coefficients of i j k

$$x = x_1 + \sigma l \quad y = y_1 + \sigma m \quad z = z_1 + \sigma n$$

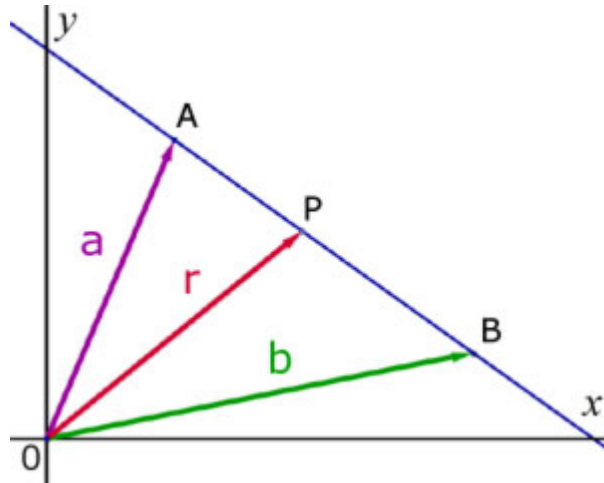
rearranging to make σ the subject

$$\sigma = \frac{x - x_1}{l}, \quad \sigma = \frac{y - y_1}{m}, \quad \sigma = \frac{z - z_1}{n}$$

hence the Cartesian equation of the line:

$$\underline{\underline{\frac{x - x_1}{l} = \frac{y - y_1}{m} = \frac{z - z_1}{n} \quad (= \sigma)}}$$

Equation of a straight line - two points given



$A(x_1 \ y_1 \ z_1)$ is a fixed point on the line

\mathbf{a} is the position vector for point A $\mathbf{a} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k}$

$B(x_2 \ y_2 \ z_2)$ is a fixed point on the line

\mathbf{b} is the position vector for point B $\mathbf{b} = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k}$

\mathbf{r} is the position vector for an arbitrary point $P(x, y, z)$ on the line.

let \overrightarrow{AB} be a vector from A to B

$$\Rightarrow \overrightarrow{AB} = \overrightarrow{OB} - \overrightarrow{OA}$$

since $b = \overrightarrow{OB}$ and $a = \overrightarrow{OA}$

$$\therefore \overrightarrow{AB} = b - a \quad (i)$$

$$\overrightarrow{AP} = \theta \overrightarrow{AB} \quad (\theta \text{ is a scalar variable})$$

substituting for \overrightarrow{AB} from (i)

$$\overrightarrow{AP} = \theta(b - a)$$

$$\overrightarrow{OP} = r$$

$$r = \overrightarrow{OA} + \overrightarrow{AP}$$

$$\underline{r = a + \theta(b - a)} \quad (\text{vector equation of the line})$$

replacing the vectors by their components

$$xi + yj + zk = x_1i + y_1j + z_1k + \theta(x_2i + y_2j + z_2k - x_1i + y_1j + z_1k)$$

expanding

$$xi + yj + zk = x_1i + y_1j + z_1k + \theta x_2i + \theta y_2j + \theta z_2k - \theta x_1i + \theta y_1j + \theta z_1k$$

factorising

$$xi + yj + zk = [x_1 + \theta(x_2 - x_1)]i + [y_1 + \theta(y_2 - y_1)]j + [z_1 + \theta(z_2 - z_1)]k$$

comparing the coefficients of i j k

$$x = x_1 + \theta(x_2 - x_1)$$

$$y = y_1 + \theta(y_2 - y_1)$$

$$z = z_1 + \theta(z_2 - z_1)$$

making θ the subject

$$\frac{x - x_1}{x_2 - x_1} = \frac{y - y_1}{y_2 - y_1} = \frac{z - z_1}{z_2 - z_1} \quad (= \theta)$$

(the Cartesian equations)

The Scalar Product

Introduction

The Scalar(or Dot Product), of two vectors **a** and **b** is written

$$\mathbf{a} \cdot \mathbf{b}$$

If the two vectors are inclined to each other by an angle(say θ) then the product is written

$$\mathbf{a} \cdot \mathbf{b} = |\mathbf{a}| \cdot |\mathbf{b}| \cos \theta \quad \text{or} \quad \mathbf{a} \cdot \mathbf{b} = ab \cos \theta$$

Even though the left hand side of the equation is written in terms of vectors, the answer is a scalar quantity.

Rules

$$\mathbf{a} \cdot \mathbf{b} = ab \cos \theta = \mathbf{b} \cdot \mathbf{a}$$

when **a** & **b** are parallel, $\theta = 0$, $\cos \theta = 1$, $\mathbf{a} \cdot \mathbf{b} = ab$
(unit vectors $\mathbf{i} \cdot \mathbf{i} = \mathbf{j} \cdot \mathbf{j} = \mathbf{k} \cdot \mathbf{k} = 1$)

when **a** & **b** are at 90°, $\theta = 90^\circ$, $\cos \theta = 0$, $\mathbf{a} \cdot \mathbf{b} = 0$
(unit vectors: $\mathbf{i} \cdot \mathbf{j} = \mathbf{j} \cdot \mathbf{i} = 0$ $\mathbf{j} \cdot \mathbf{k} = \mathbf{k} \cdot \mathbf{j} = 0$ $\mathbf{k} \cdot \mathbf{i} = \mathbf{i} \cdot \mathbf{k} = 0$)

if $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$ and $\mathbf{b} = b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}$

then

$$\mathbf{a} \cdot \mathbf{b} = a_1b_1 + a_2b_2 + a_3b_3$$

$$|\mathbf{a}|^2 = \mathbf{a} \cdot \mathbf{a} = a_1^2 + a_2^2 + a_3^2$$

$$\mathbf{a} \cdot (\mathbf{b} + \mathbf{c}) = \mathbf{a} \cdot \mathbf{b} + \mathbf{a} \cdot \mathbf{c} \qquad \mathbf{a} \cdot (\mathbf{b} - \mathbf{c}) = \mathbf{a} \cdot \mathbf{b} - \mathbf{a} \cdot \mathbf{c}$$

$$(\mathbf{a} + \mathbf{b}) \cdot \mathbf{c} = \mathbf{a} \cdot \mathbf{c} + \mathbf{b} \cdot \mathbf{c} \qquad (\mathbf{a} - \mathbf{b}) \cdot \mathbf{c} = \mathbf{a} \cdot \mathbf{c} - \mathbf{b} \cdot \mathbf{c}$$

$$(\lambda \mathbf{a}) \cdot \mathbf{b} = \lambda(\mathbf{a} \cdot \mathbf{b}) = \mathbf{a} \cdot (\lambda \mathbf{b})$$

$$\cos \theta = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| \cdot |\mathbf{b}|}$$

Example #1

Given that $\mathbf{a} = 3\mathbf{i} - \mathbf{j} + 2\mathbf{k}$ and $\mathbf{b} = 2\mathbf{i} + \mathbf{j} - 2\mathbf{k}$,
find $\mathbf{a} \cdot \mathbf{b}$ and the included angle between the vectors to 1 d.p.

$$\begin{aligned} \mathbf{a} \cdot \mathbf{b} &= (3\mathbf{i} - \mathbf{j} + 2\mathbf{k}) \cdot (2\mathbf{i} + \mathbf{j} - 2\mathbf{k}) \\ &= 6 - 1 - 4 \\ &= 1 \end{aligned}$$

$$\underline{\mathbf{a} \cdot \mathbf{b} = 1}$$

$$\begin{aligned} |\mathbf{a}|^2 &= \mathbf{a} \cdot \mathbf{a} \\ &= (3\mathbf{i} - \mathbf{j} + 2\mathbf{k}) \cdot (3\mathbf{i} - \mathbf{j} + 2\mathbf{k}) \\ &= 9 + 1 + 4 \\ &= 14 \end{aligned}$$

$$|\mathbf{a}| = \sqrt{14}$$

$$\begin{aligned} |\mathbf{b}|^2 &= \mathbf{b} \cdot \mathbf{b} \\ &= (2\mathbf{i} + \mathbf{j} - 2\mathbf{k}) \cdot (2\mathbf{i} + \mathbf{j} - 2\mathbf{k}) \\ &= 4 + 1 + 4 \\ &= 9 \end{aligned}$$

$$|\mathbf{b}| = 3$$

with θ the included angle

$$\cos \theta = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| \cdot |\mathbf{b}|}$$

substituting for $\mathbf{a} \cdot \mathbf{b}$, $|\mathbf{a}|$, $|\mathbf{b}|$

$$\cos \theta = \frac{1}{\sqrt{14} \times 3} = \frac{1}{11.225}$$

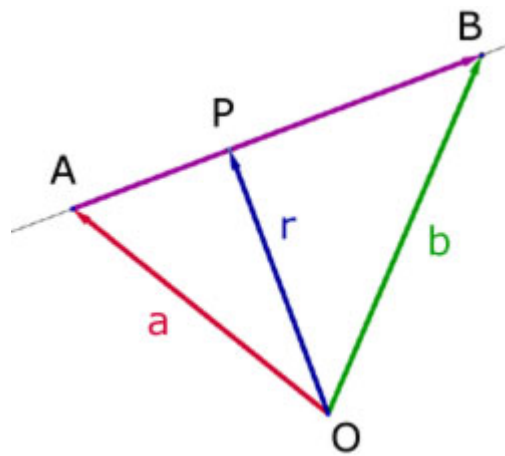
$$\Rightarrow \theta = 84.89^\circ$$

the angle between a and b is 84.9° (1 d.p.)

Example #2

What is the vector equation describing the straight line passing through the points $A(-8, 1, -2)$ and $B(10, -1, 3)$?

Find the coordinates of a point P on AB such that OP is perpendicular to AB (origin O), hence find the distance OP to 2d.p.



given points: $A(-8, 1, -2)$ $B(10, -1, 3)$

$$\begin{aligned}\Rightarrow \overrightarrow{AB} &= (-8 + 10)\mathbf{i} + (1 - 1)\mathbf{j} + (-2 + 3)\mathbf{k} \\ &= 2\mathbf{i} + 0 + \mathbf{k} \\ &= 2\mathbf{i} + \mathbf{k}\end{aligned}$$

if \mathbf{r} is the position vector for point P

the vector equation of line AB is:

$$\underline{\mathbf{r} = \mathbf{a} + \lambda(\overrightarrow{AB})}$$

$$\begin{aligned}\mathbf{r} &= \mathbf{a} + \lambda(2\mathbf{i} + \mathbf{k}) \\ &= -8\mathbf{i} + \mathbf{j} - 2\mathbf{k} + \lambda(2\mathbf{i} + \mathbf{k}) \\ &= -8\mathbf{i} + \mathbf{j} - 2\mathbf{k} + 2\lambda\mathbf{i} + \lambda\mathbf{k} \\ &= (2\lambda - 8)\mathbf{i} + \mathbf{j} + (\lambda - 2)\mathbf{k}\end{aligned}$$

\therefore coords. of any point P on AB are $(2\lambda - 8, 1, \lambda - 2)$

for \overrightarrow{OP} to be perpendicular to \overrightarrow{AB}

$$\begin{aligned}\Rightarrow \overrightarrow{OP} \cdot \overrightarrow{AB} &= 0 \\ \Rightarrow [(2\lambda - 8)\mathbf{i} + \mathbf{j} + (\lambda - 2)\mathbf{k}] \cdot [2\mathbf{i} + \mathbf{k}] &= 0 \\ \Rightarrow 2(2\lambda - 8) + 0 + 1(\lambda - 2) &= 0 \\ \Rightarrow 4\lambda - 16 + \lambda - 2 &= 0 \\ \Rightarrow 5\lambda &= 18 \\ \Rightarrow \lambda &= 3.6\end{aligned}$$

substituting into coords. for $P(2\lambda - 8, 1, \lambda - 2)$

$$\begin{aligned}\Rightarrow P(2 \times 3.6 - 8, 1, 3.6 - 2) \\ \Rightarrow P(-0.8, 1, 1.6)\end{aligned}$$

$$\begin{aligned}\therefore |\overrightarrow{OP}| &= \sqrt{(-0.8)^2 + (1)^2 + (1.6)^2} \\ &= \sqrt{(0.64) + (1) + (2.56)} \\ &= 2.04939\end{aligned}$$

perp. dist. between O and AB is 2.05 (2d.p.)

Notes

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